## 1 Ciarlet's elastic energy

The Ciarlet-Geymonat strain energy is close to the St.-Venant-Kirchhoff strain energy, but in contrast to the latter it is polyconvex in  $\mathbf{F}$ ,

$$
w(\mathbf{F}) = \frac{\lambda}{4} (\mathbf{I} - \ln \mathbf{I}) + \frac{\mu}{2} (I - \ln \mathbf{I})
$$
\n(1)

It serves as starting point for our elastic strain gradient extension. The roman numbers  $I$  and  $I\!I\!I$  denote the first and third principle invariants of the Cauchy-Green stretch tensors **B** and **C**,  $\lambda$  and  $\mu$  are Lamé's constants.

## 2 Strain gradient extension

To comply with the principle of invariance under rigid body motion,  $w$  is best formulated in terms of material deformation measures. While we use  $\mathbf{C} = \mathbf{F}^T \mathbf{F}$  for the first gradient, we need to define a similar material stretch measure for the second gradient  $\mathbf{F}_3 = \mathbf{x} \otimes \nabla_0 \otimes \nabla_0$ . A canonical extension is

$$
\mathbf{C}_3 = \mathbf{F}^T \mathbf{F}_3. \tag{2}
$$

A simple invariant is the norm, which we term  $g$  to indicate the strain gradient contribution,

$$
g = \sqrt{\mathbf{C}_3 \cdots \mathbf{C}_3}.\tag{3}
$$

We extend  $w$  by a summand that contains  $q$ . We choose

$$
w_g(\mathbf{F}) = \frac{\lambda}{4}(\mathbf{I} - \ln \mathbf{I}) + \frac{\mu}{2}(I - \ln \mathbf{I}) + \frac{\alpha}{2}g^2,
$$
\n<sup>(4)</sup>

where  $\alpha$  is a new material parameter.

## 3 Stress-Strain relation

We consider the first Piola-Kirchhoff stresses  $T$  as most practical for our purpose. Especially from an implementation point of view, we can write down the local balance of momentum by using the material nabla operator  $\nabla_0$ 

$$
\rho(\mathbf{a} - \mathbf{b}) = \mathbf{T} \cdot \nabla_0 - \mathbf{T}_3 \cdot (\nabla_0 \otimes \nabla_0).
$$
\n(5)

Thus we need in the FE implementation the same operators  $\nabla_0$  and  $\nabla_0 \otimes \nabla_0$  for calculating the first and second gradient and for calculating the residuals, which simplifies the implementation considerably. We refer to  $T_3$ thus as the first Piola-Kirchhoff stress tensor of third order, which is derived from  $w$  similar to the usual first Piola-Kirchhoff stresses,

$$
\mathbf{T} = \frac{\partial w}{\partial \mathbf{F}},\tag{6}
$$

$$
\mathbf{T}_3 = \frac{\partial w}{\partial \mathbf{F}_3}.\tag{7}
$$

We summarize  $\rho_0$  with the material constants, since it is also a constant. The derivatives evaluate to

$$
\mathbf{T} = \mu \mathbf{F} + \left(\frac{\lambda}{2} \left(\mathbf{I} \mathbf{I} - 1\right) - \mu\right) \mathbf{F}^{-T} + \alpha F_{mjl} C_{njl} \mathbf{e}_m \otimes \mathbf{e}_n, \tag{8}
$$

$$
\mathbf{T}_3 = \alpha \mathbf{F} \mathbf{C}_3 = \alpha \mathbf{B} \mathbf{F}_3. \tag{9}
$$

The number of indices distinguishes  $\mathbf{F}, \mathbf{F}_3$  and  $\mathbf{C}, \mathbf{C}_3$  in the index notation. Additional to the stress-strain (gradient) relation, we need the linearisations,

$$
\frac{\partial \mathbf{T}}{\partial \mathbf{F}} = \mu \mathbb{I} - \left(\frac{\lambda}{2}(\mathbf{I}\mathbf{I} - 1) - \mu\right) (F_{jk}^{-1} F_{il}^{-T})_{ijkl} + \lambda \mathbf{I} \mathbf{F}^{-T} \otimes \mathbf{F}^{-T} + \alpha (F_{ixy} F_{kxy} \delta_{jl})_{ijkl},\tag{10}
$$

$$
\frac{\partial \mathbf{T}}{\partial \mathbf{F}_3} = \alpha (\delta_{ik} C_{jlm} + F_{kj} F_{ilm})_{ijklm},\tag{11}
$$

$$
\frac{\partial \mathbf{T}_3}{\partial \mathbf{F}} = \alpha (\delta_{il} C_{mjk} + F_{im} F_{ljk})_{ijklm},\tag{12}
$$

$$
\frac{\partial \mathbf{T}_3}{\partial \mathbf{F}_3} = \alpha \mathbf{B} \mathbb{I}^6 = \alpha (B_{il} \delta_{jm} \delta_{kn})_{ijklmn} \tag{13}
$$